

**The program of the final control in the discipline  
«Geometric control theory»**

**Specialty –7M05407 Mathematics**

**Course – 2**

**Language of study – Kazakh, language – English  
2022, autumn semester**

**Form of final control** – standard exam, oral, offline

**Time to prepare an answer** – 1 hour

**Evaluation Policy** – standard

**Exam time** – according to the schedule

**List of questions submitted for the exam**

Item № 1. Theoretical questions (Maximum score - 30 points)

1. Function minimization problems. Stationary condition.
2. Maximum principle for the standard optimization problem.
3. Convergence of the iterative method for the example of optimization problem.
4. Theorem of optimal control uniqueness.
5. Theorem of sufficient optimality conditions.
6. Singular controls.
7. Example of non-existence of optimal control for the system with free final state.
8. Theorem of optimal control existence.
9. Tihonov well-posedness of the problem.
10. Hadamard well-posedness of the problem.
11. Optimality conditions for the system with fixed final state.
12. Example of non-existence of optimal control for the system with fixed final state.
13. Optimality conditions for the system with isoperimetric condition.
14. Example of non-sufficient optimality condition for the system with isoperimetric condition.
15. Example of extremal bifurcation.

Item № 2. Development of an algorithm for solving a concrete optimization problem described by differential equations. (Maximum score - 50 points)

1. Optimization problem for the concrete system with free final state.
2. Optimization problem for the concrete system with free fixed state.
3. Optimization problem for the concrete system with the isoperimetric condition.

Item № 3. Diagnosis of the situation in the practical solving of the problem. (Maximum score - 20 points).

1. It should indicate what effect is observed, what may be its causes and what should be done to overcome the difficulties encountered.
2. Algorithm divergence
3. Divergence of a sequence of controls under convergence of a sequence of functionals.
4. Obtaining different results with different initial approximations.
5. A large change in results with a small change in the parameters of the problem.